John Dallas Cast

3112 Abell Avenue jcast1@jhu.edu Baltimore, MD 21218 www.johndallascast.com 217-260-9480 Full-Stack Software Development: 7+ years **Computer Vision / Deep Learning:** 5+ years **EDUCATION** JOHNS HOPKINS UNIVERSITY, Baltimore, MD Master of Science - Engineering Degree in Robotics Expected Apr, 2023 • Focus: Perception STANFORD UNIVERSITY, Palo Alto, CA • Master of Science Degree in Electrical Engineering June, 2015 • **Focus:** Lasers, Optoelectronics, Quantum Electronics Bachelor of Science Degree in Electrical Engineering June, 2012 RELEVANT COURSEWORK AND SKILLS Computer Vision, Augmented Reality, Deep Learning, Kinematics/Dynamics, Keras, Tensorflow, PyTorch, Python, Unity, Hololens 2, Coffeescript/Javascript, C++, Arduino/Raspberry Pi, Meteor, MongoDB WORK EXPERIENCE JHUROVII, Baltimore, MD Intern Jun 2022 – Present • Worked in team to assemble all major sub-systems (e.g. chassis, electronics, code, housing, etc.) Wrote and debugged thruster node in ROS • Designed CAD model for thruster oil compensator Characterized thrusters Currently assembling endcaps for housing and will water test the housing soon AQUAEYE.AI, Palo Alto, CA Sole Proprietor Aug 2019 – Apr 2021 • Trained, tested and deployed fish identification tensorflow models Configured cloud computing for tensorflow models Built website to host models with live view of fish exhibits Collected/cleaned train/val/test databases (2D video/2D images) Produced synthetic train/val/test data (2D images) Software Engineer MATTHEWS SOUTH, Palo Alto, CA Jan 2015 – July 2021 Authored most of Front-End and helped design/write Back-End API for Front-End Built projects in financial modeling/NLP Machine Learning Researcher DOLPHIN AI, Palo Alto, CA Jan 2017 – Jan 2019 • Identified / Classified roof features in aerial imagery Designed/Trained CNNs for edge-detection / roof-identification / roof-segmentation Collected/Annotated 2D drone/satellite Image Data Implemented research papers Machine Learning Engineer TARSIER, Palo Alto, CA Sept – Dec 2016 Built autonomous recognition of UAVs in image/video (2D video/2D images) • Wrote GUI in python Trained and docker-installed core model, Inception V3 in Keras + Tensorflow

Team received Honorable Mention Award in MD5 Hackathon

RESEARCH EXPERIENCE

- MSE in Robotics Thesis (Ongoing): Cooperative, Real-time, Augmented Reality Professor Mathias Unberath Johns Hopkins University
- Paid Lab Assistant: JHU-ROVII Project Professor Louis Whitcomb Johns Hopkins University
- Summer Research: LASER characterization Professor Gary Swenson University of Illinois Urbana-Champaign
- Research Assistant: SnowFort Project, Fiber Optic Gyroscope Project, Thunderstorm UAV Stanford University

PUBLICATIONS

• Wenhao Gu, Jonathan Knopf, **John Cast**, Leonardo Guibert and Mathias Unberath. Nail it! Vision-based Drift Correction For Accurate Mixed Reality Surgical Guidance. 2022.